

## Radial grippers DHRS

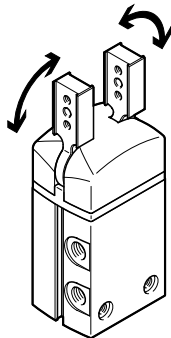
**FESTO**



## Characteristics

### At a glance

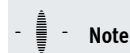
General



- Lateral gripper jaw support for high torque loads
- Self-centring
- Gripper jaw centring options
- Max. repetition accuracy
- Gripping force retention
- Internal fixed flow control
- Wide range of adaptation options on the drives
- Sensor technology:
  - Adaptable position sensor for the small gripper sizes
  - Integrated proximity switches for the medium and large gripper sizes

### Flexible range of applications

- Can be used as a double-acting and single-acting gripper
- Compression spring for supporting or backing up the gripping forces
- Suitable for external and internal gripping



#### Note

Engineering software for gripper selection → [www.festo.com](http://www.festo.com)

### Position sensing/force control

With position transmitter SMAT-8M, SDAT



Analogue position feedback possible

- Analogue output
  - 0 ... 10 V
  - 4 ... 20 mA

With proportional-pressure regulator VPPM



Infinite adjustment of the gripping force possible

- Setpoint value input
  - 0 ... 10 V
  - 4 ... 20 mA

With proximity switch SMT-8G



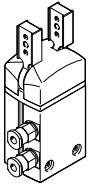
Detecting multiple positions:

- Open
- Closed
- Workpiece gripped

## Characteristics

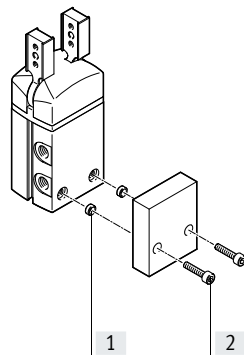
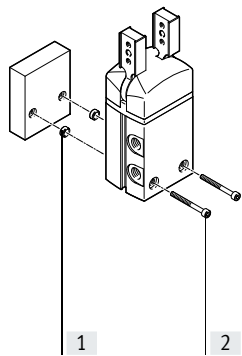
### Supply ports

At the side

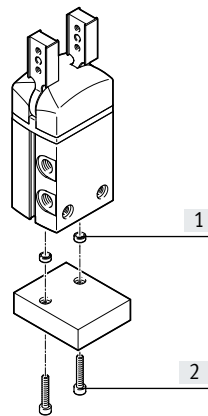


### Mounting options

At the side

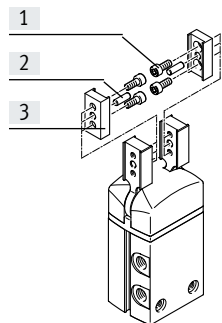


From underneath



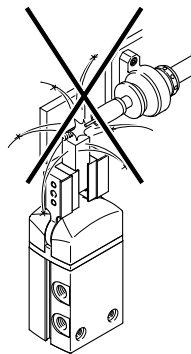
- [1] Centring sleeves
- [2] Retaining screws

### Mounting options for external gripper fingers

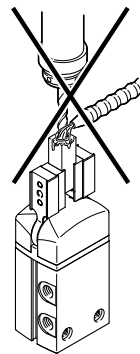


- [1] Retaining screws
- [2] Centring pins
- [3] Gripper finger

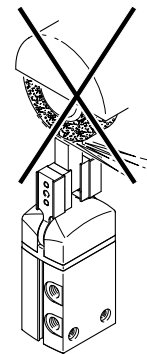
**Note**  
These grippers are not designed for the following or similar applications:



- Welding spatter



- Machining
- Aggressive media

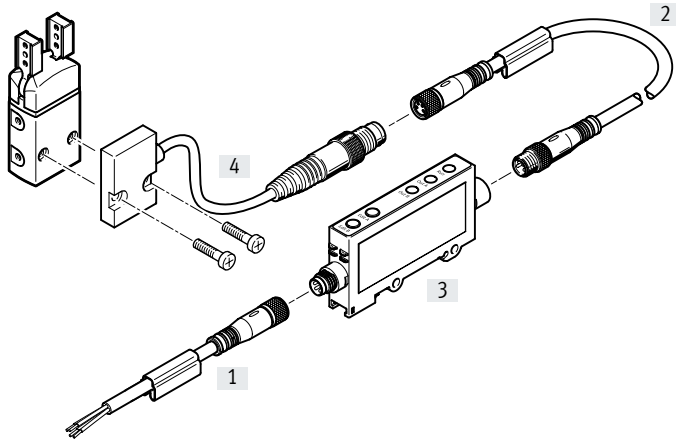


- Grinding dust

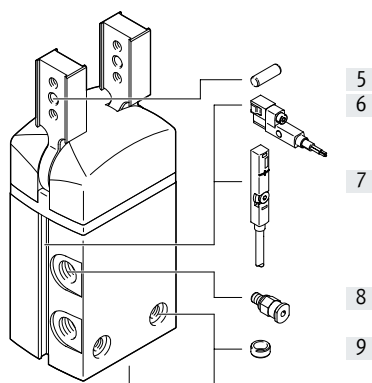
## Peripherals overview

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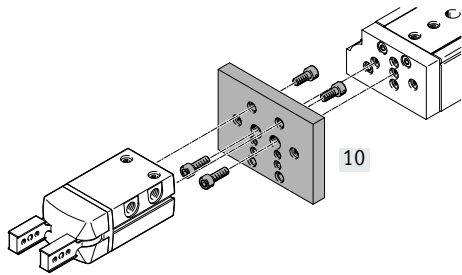
DHRS-10



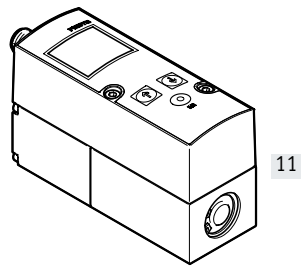
DHRS-16 ... 40



### System product for handling and assembly technology



### Proportional-pressure regulator VPPM



## Peripherals overview

Accessories				
	Type	For size	Description	→ Page/Internet
[1]	Connecting cable NEBU	10	<ul style="list-style-type: none"> <li>Connection between signal converter and controller</li> </ul>	19
[2]	Connecting cable NEBU	10	<ul style="list-style-type: none"> <li>Connection between position sensor and signal converter</li> </ul>	19
[3]	Signal converter SVE4	10	<ul style="list-style-type: none"> <li>For evaluating signals for position sensor SMH-S1</li> </ul>	19
[4]	Position sensor SMH-S1	10	<ul style="list-style-type: none"> <li>Adaptable sensors for sensing the piston position, can be integrated</li> </ul>	19
[5]	Centring pin	10... 40	<ul style="list-style-type: none"> <li>For centring the gripper fingers on the gripper jaws</li> </ul>	-
[6]	Proximity switch SMT-8G	16 ... 40	<ul style="list-style-type: none"> <li>For sensing the piston position</li> <li>Proximity switch does not project past the housing at the bottom</li> </ul>	20
[7]	Position transmitter SMAT-8M	16 ... 40	<ul style="list-style-type: none"> <li>Continuously senses the position of the piston. It has an analogue output with an output signal relative to the piston position.</li> </ul>	20
	Position transmitter SDAT	32, 40		
[8]	Push-in fitting QS	10... 40	<ul style="list-style-type: none"> <li>For connecting compressed air tubing with standard O.D.</li> </ul>	qs
[9]	Centring sleeve ZBH	10... 40	<ul style="list-style-type: none"> <li>For centring the gripper during mounting</li> <li>2 centring sleeves included in the scope of delivery of the gripper</li> </ul>	19
[10]	Adapter kit DHAA, HMSV, HAPG, HAPS, HMVA	10... 40	<ul style="list-style-type: none"> <li>Connecting plate between drive and gripper</li> </ul>	16
[11]	Proportional-pressure regulator VPPM	10... 40	<ul style="list-style-type: none"> <li>For infinite adjustment of the gripping force</li> </ul>	vppm

Type codes

001	Series
DHRS	Radial gripper

002	Size
10	10
16	16
25	25
32	32
40	40

003	Position sensing
A	For proximity sensor

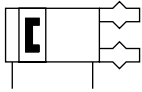
004	Gripping force backup
	None
NC	N/O contact

## Data sheet

## Function

Double-acting

DHRS-...A



Size  
10 ... 40 mm

Opening angle  
180°



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## Function variants

Single-acting or  
with gripping force retention ...  
... closing DHRS-...-NC



General technical data		10	16	25	32	40
Size		10	16	25	32	40
Design		Force-guided motion sequence				
Mode of operation		Double-acting				
Gripper function		Radial				
Guide		Plain-bearing guide				
Gripping force retention		–	NC	NC	NC	NC
Number of gripper jaws		2				
Opening angle per gripper jaw	[°]	90				
Pneumatic connection		M3	M3	M5	G1/8	G1/8
Repetition accuracy <sup>1)</sup>	[mm]	≤ 0.1				
Max. interchangeability	[mm]	≤ ±0.2				
Max. operating frequency	[Hz]	4			3	
Rotational symmetry	[mm]	< ∅ 0.2				
Position sensing		Via position sensor		Via proximity switch, position transmitter		
Type of mounting		With through-hole and centring sleeve				
		With female thread and centring sleeve				
Mounting position		Any				

1) Under constant exposure to operating conditions, end-position drift occurs, in the direction of movement of the gripper jaws, at 100 consecutive strokes

Operating and environmental conditions		10	16	25	32	40
Min. operating pressure						
DHRS-...A	[bar]	2				
DHRS-...A-NC	[bar]	–	4			
Max. operating pressure	[bar]	8				
Operating medium		Compressed air to ISO 8573-1:2010 [7:4:4]				
Note on operating/pilot medium		Lubricated operation possible (in which case lubricated operation will always be required)				
Ambient temperature <sup>1)</sup>	[°C]	+5 ... +60				
Corrosion resistance CRC <sup>2)</sup>		1				

1) Note operating range of proximity switches

2) Corrosion resistance class CRC 1 to Festo standard FN 940070

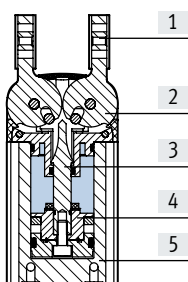
Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Weight [g]		10	16	25	32	40
DHRS-...A		44	114	270	480	829
DHRS-...A-NC		–	118	277	490	844

## Data sheet

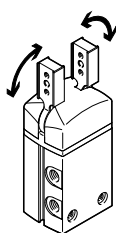
### Materials

Sectional view



Radial grippers		
[1]	Gripper jaws	High-alloy stainless steel
[2]	Cover cap	Polyamide
[3]	Link	Tempered steel
[4]	Piston	Polyacetal
[5]	Housing	Hard anodised wrought aluminium alloy
-	Seals	NBR
-	Note on materials	Free of copper and PTFE RoHS-compliant

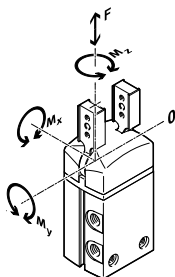
### Total gripping torque [Ncm] at 6 bar



The gripping torque is not constant across the opening angle  
→ page 12

Size		10	16	25	32	40
DHRS-...A	Opening	21	62	233	423	725
	Closing	15	55	215	390	660

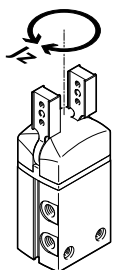
### Static characteristic load values at the gripper jaws



The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional weight forces created by the workpiece or external gripper fingers and acceleration forces during movement.  
The zero coordinate line (gripper jaw guide) must be taken into consideration when calculating the torques.

Size		10	16	25	32	40
Max. permissible force $F_z$	[N]	30	40	75	120	200
Max. permissible torque $M_x$	[Nm]	0.8	1.3	3.2	6.2	14
Max. permissible torque $M_y$	[Nm]	0.8	1.3	3.2	6.2	14
Max. permissible torque $M_z$	[Nm]	0.8	1.3	3.2	6.2	14

### Mass moment of inertia [kgm<sup>2</sup>x10<sup>-4</sup>]



Mass moment of inertia of the radial gripper in relation to the central axis, without external gripper fingers, with no load.

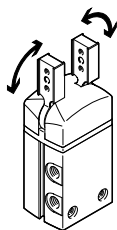
Size		10	16	25	32	40
DHRS-...A		0.03	0.14	0.69	1.66	4.18
DHRS-...A-NC		-	0.15	0.71	1.69	4.24



## Data sheet

### Opening and closing times [ms] at 6 bar

Without external gripper fingers

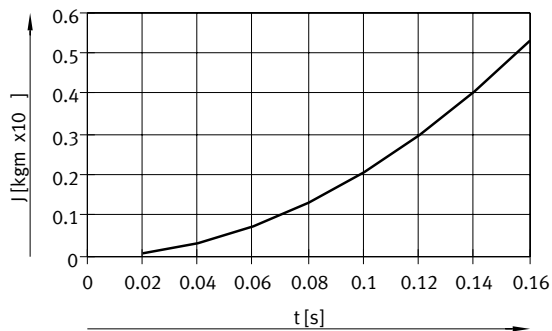


The indicated opening and closing times [ms] were measured at room temperature at an operating pressure of 6 bar with the gripper horizontally mounted and without additional gripper fingers (mean values shown). The grippers must be throttled for greater applied loads. Opening and closing times must then be adjusted accordingly.

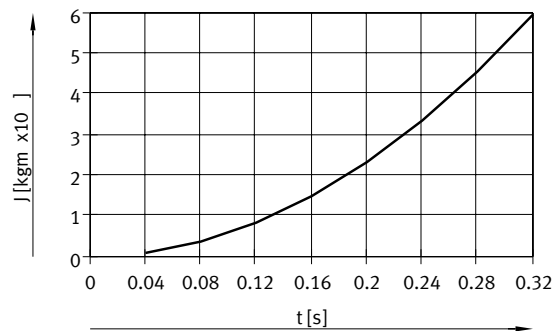
Size		10	16	25	32	40
<b>Without external gripper fingers</b>						
DHRS-...-A	Opening	35	61	102	111	113
	Closing	91	63	105	119	142
DHRS-...-A-NC	Opening	-	75	150	131	151
	Closing	-	43	96	88	110

### Opening and closing times $t$ to be set at 6 bar as a function of mass moment of inertia of the gripper fingers

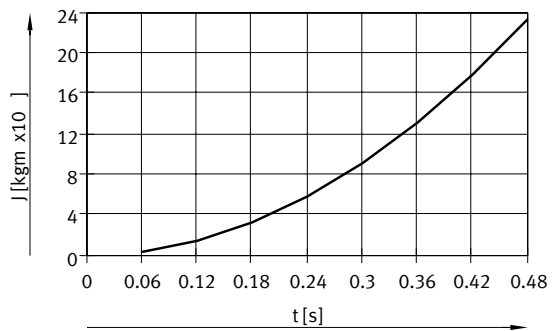
DHRS-10



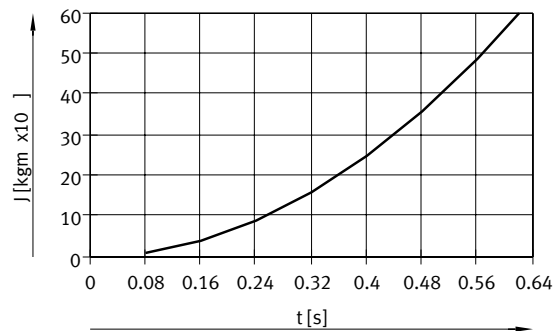
DHRS-16



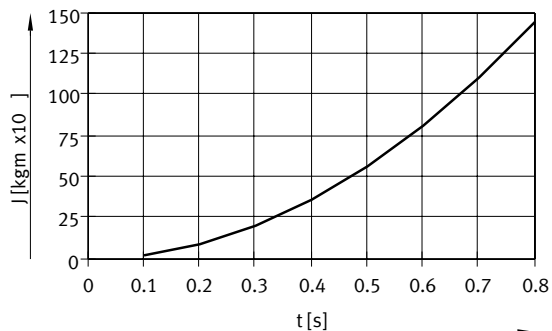
DHRS-25



DHRS-32



DHRS-40



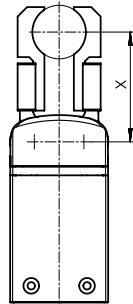
Data sheet

Gripping force  $F_H$  per gripper jaw as a function of operating pressure and lever arm  $x$

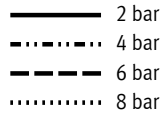
The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.

The gripping torque is not constant across the opening angle

→ page 12.

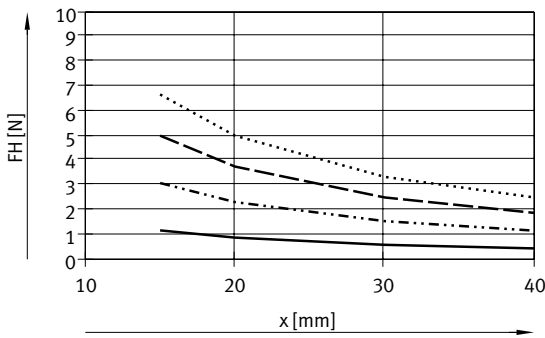


**Note**  
Engineering software  
for gripper selection  
→ [www.festo.com](http://www.festo.com)

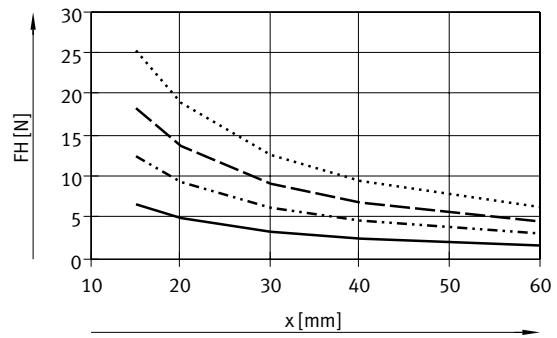


External gripping (closing)

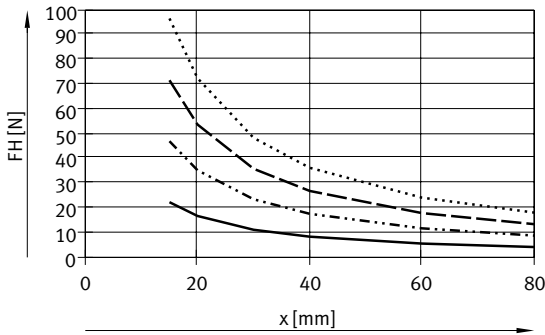
DHRS-10



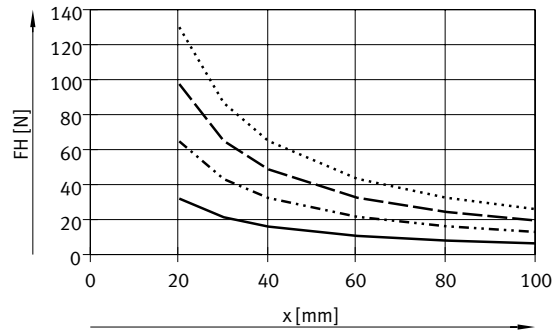
DHRS-16



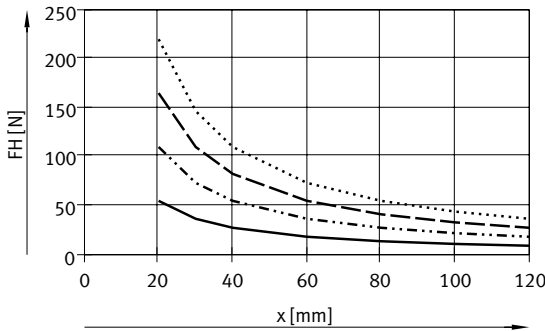
DHRS-25



DHRS-32



DHRS-40



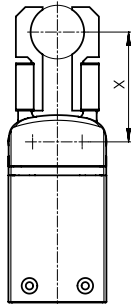
## Data sheet


### Gripping force $F_H$ per gripper jaw as a function of operating pressure and lever arm $x$

The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.

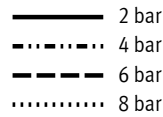
The gripping torque is not constant across the opening angle

→ page 12.



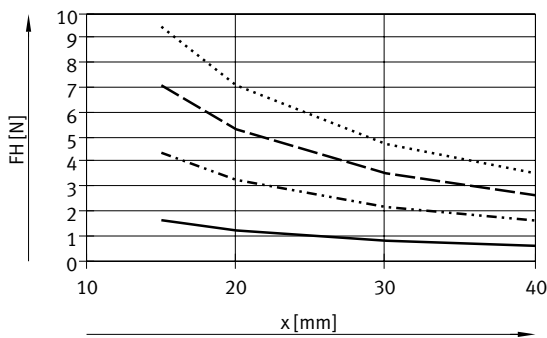
 **Note**

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for gripper selection  
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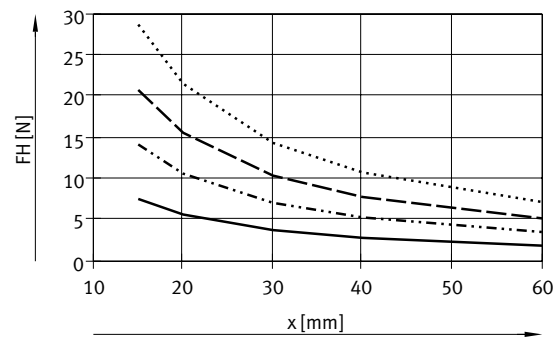


### Internal gripping (opening)

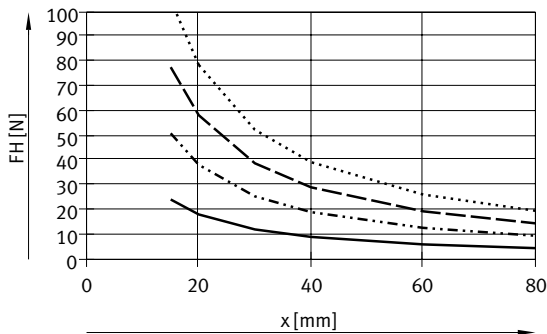
DHRS-10



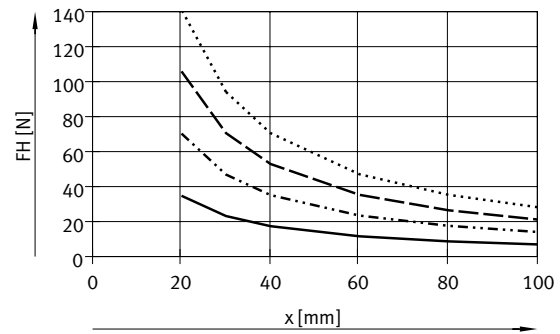
DHRS-16



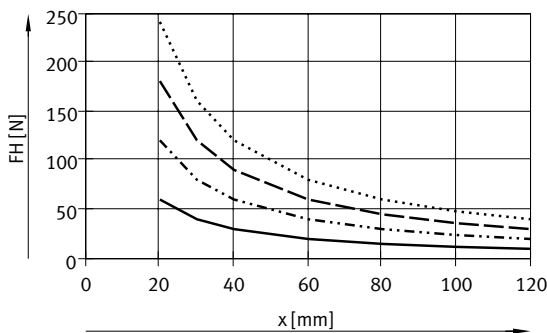
DHRS-25



DHRS-32



DHRS-40



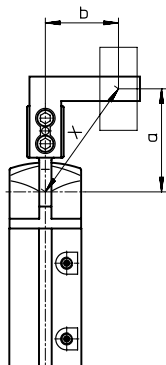
## Data sheet

### Gripping force $F_H$ per gripper jaw at 6 bar as a function of lever arm $x$ and eccentricity $a$ and $b$

The following formula must be used to calculate the lever arm  $x$  with eccentric gripping:

$$x = \sqrt{a^2 + b^2}$$

The gripping force  $F_H$  can then be read from the graphs (→ page 10/11) using the calculated value  $x$ .

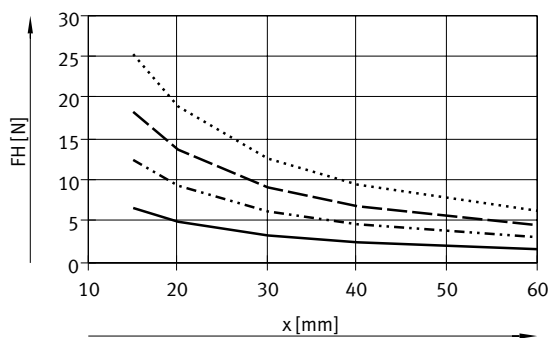


### Calculation example

Given:  
 Distance  $a = 25$  mm  
 Distance  $b = 20$  mm  
 To be calculated:  
 The gripping force at 6 bar with a DHRS-16, used as an external gripper

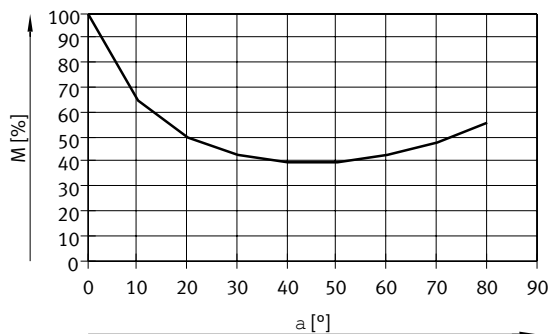
Approach:  
 Calculating the lever arm  $x$   
 $x = \sqrt{25^2 + 20^2}$   
 $x = 32$  mm

The graph (→ page 10) gives a value for the gripping force of  $F_H = 8$  N.



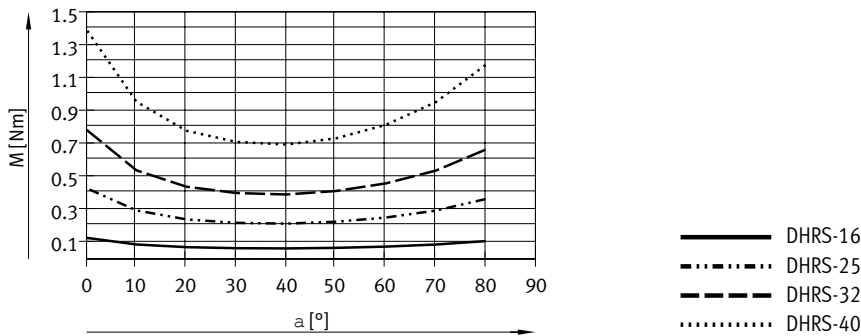
### Torque curve $M$ as a function of opening angle $\alpha$

The drive principle of the gripper jaws means that the torque is not constant across the opening angle. The percentage of torque available in each case can be determined from the graph. Opening angle of  $0^\circ$  means: parallel gripper jaw position



Data sheet

Spring torque  $M_F$  as a function of opening angle  $\alpha$



Determining the actual gripping torques  $M_{Grtotal}$  for DHRS-...-NC as a function of application

The radial gripper with integrated spring, type DHRS-...-NC (closing gripping force retention), can be used as:

- Single-acting gripper
- Gripper with supplementary gripping force
- Gripper with gripping force retention

To calculate the available gripping torque  $M_{Grtotal}$  (per gripper jaw), the data from the graphs for gripping force  $F_H$  (→ page 10/11),

$$M_{Gr} = F_H * x * M \text{ [%]}$$

torque curve  $M$  (→ page 12) and spring torque  $M_F$  (→ page 13) must be combined accordingly.

- $M_{Gr}$  Gripping torque
- $F_H$  Gripping force
- $x$  Lever arm
- $M$  Torque curve

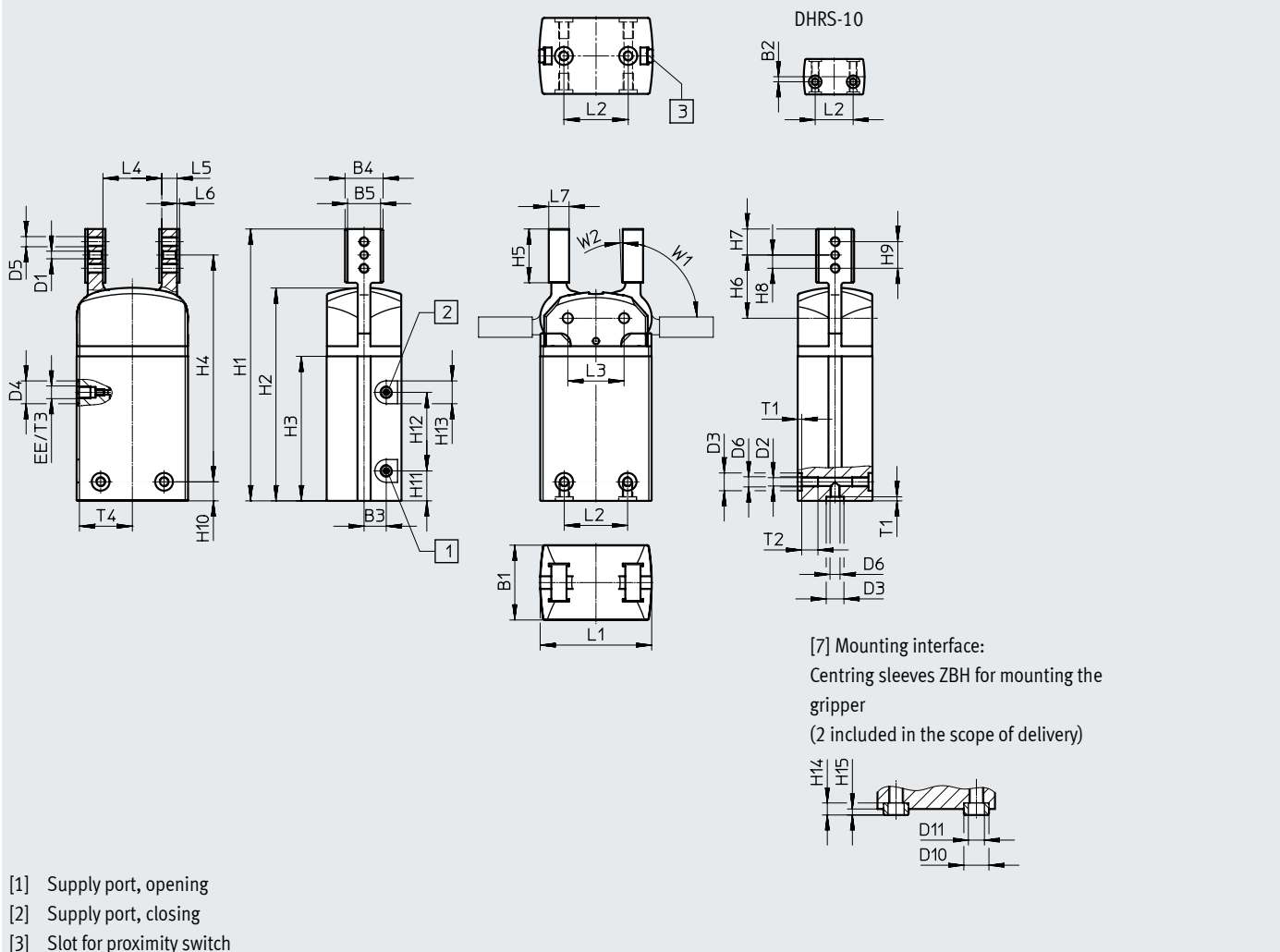
Application

Single-acting	Supplementary gripping force	Gripping force retention
<ul style="list-style-type: none"> <li>• Gripping with spring force: <math>M_{Grtotal} = M_F</math></li> <li>• Gripping with pressure force: <math>M_{Grtotal} = M_{Gr} - M_F</math></li> </ul>	<ul style="list-style-type: none"> <li>• Gripping with pressure and spring force: <math>M_{Grtotal} = M_{Gr} + M_F</math></li> </ul>	<ul style="list-style-type: none"> <li>• Gripping with spring force: <math>M_{Grtotal} = M_F</math></li> </ul>

Data sheet

Dimensions

Download CAD data → [www.festo.com](http://www.festo.com)



Size	B1	B2 <sup>1)</sup>	B3	B4	B5 +0.03/ +0.01	D1 ∅ H8	D2 ∅ +0.1	D3 ∅ H8/h7	D4 ∅	D5	D6
[mm]	±0.05										
10	14	2	2	8.5	6.5	2	2.4	5	7	M2.5	M3
16	19	–	5.8	14	10	2	2.5	5	–	M3	M3
25	29.5	–	8.75	15	13	3	3.3	7	9	M4	M4
32	38	–	11	16	14	4	5.1	9	15	M5	M6
40	49	–	11	24	20	5	6.4	12	15	M6	M8

Size	D10 ∅ h7	D11 ∅	EE	H1	H2	H3	H4 ±0.25	H5 ±0.2	H6 ±0.05	H7 –0.1
[mm]										
10	5	3.2	M3	60.8	46	30.8	42.25	13.8	14.95	6.25
16	5	3.2	M3	88.2	70.5	49	73.7	16.5	19.7	7
25	7	5.3	M5	107.2	84	57	89.45	21.2	24.95	10.25
32	9	6.4	G1/8	128.5	96.2	65	103.5	29.5	32	14
40	12	10.3	G1/8	140	108.4	71.5	108.7	29.5	33.7	13.8

1) Tolerance for centring hole ±0.02 mm; tolerance for thread ±0.1 mm

## Data sheet

Size	H8	H9	H10 <sup>2)</sup>	H11	H12	H13	H14	H15	L1	L2 <sup>1)</sup>	L3
[mm]							-0.2	-0.3	±0.05		±0.02
10	4	8	12.3	8.8	16	7	2.4	1.2	24	15	12.4
16	4	8	7.5	12.25	23	7	2.4	1.2	33.4	16	17
25	5.25	10.5	7.5	11.8	31	9	3	1.4	44	25	22.2
32	7	14	11	20	25	15	4	1.9	51	29	25.8
40	8	16	17.5	9	46	15	5	2.4	59	33	30

Size	L4	L5	L6	L7	T1	T2	T3	T4	W1	W2
[mm]		±0.05			+0.1	+1	+0.5		±2°	+3°
10	12	4	0.5	5	1.2	through	3.5	11.6	90	2
16	21	4	1	6	1.2	5.8	4.5	16	90	2
25	23.2	6	1	8	1.6	6.4	4.5	21	90	2
32	24.8	8	1	10	2.1	12.9	6.5	24	90	2
40	29.6	10	1	12	2.6	13.4	6	28.4	90	2

1) Tolerance for centring hole ±0.02 mm; tolerance for thread ±0.1 mm

2) Tolerance for centring hole ±0.05 mm; tolerance for thread ±0.1 mm


## Ordering data

Size [mm]	Double-acting without compression spring		Single-acting or with gripping force retention	
	Part no.	Type	Closing Part no.	Type
10	<b>1310159</b>	<b>DHRS-10-A</b>	-	
16	<b>1310160</b>	<b>DHRS-16-A</b>	<b>1310161</b>	<b>DHRS-16-A-NC</b>
25	<b>1310162</b>	<b>DHRS-25-A</b>	<b>1310163</b>	<b>DHRS-25-A-NC</b>
32	<b>1310164</b>	<b>DHRS-32-A</b>	<b>1310165</b>	<b>DHRS-32-A-NC</b>
40	<b>1310166</b>	<b>DHRS-40-A</b>	<b>1310167</b>	<b>DHRS-40-A-NC</b>

Accessories



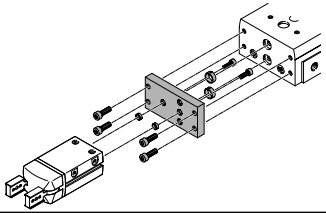
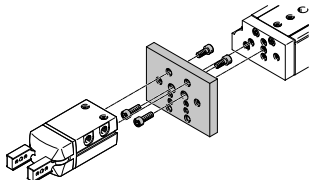
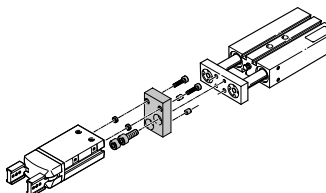
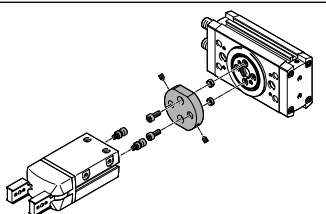
Adapter kit  
HMSV, HAPG, DHAA

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 **Note**  
The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit

Download CAD data → [www.festo.com](http://www.festo.com)

Combination	Drive size	Gripper size	Mounting option		Adapter kit CRC <sup>1)</sup>		Type
					Part no.		
	<b>DGST</b>	<b>DHRS</b>			<b>DHAA</b>		
	10	10	■	■	2	8161907	DHAA-G-G8-10-B20-10
	12	16	■	■		8161909	DHAA-G-G8-12-B20-16
	16	16	■	■		8161908	DHAA-G-G8-16-B20-16
	20	25	■	■		8161905	DHAA-G-G8-20-B20-25
	25	32	■	■		8161906	DHAA-G-G8-25-B20-32
	<b>DGSL</b>	<b>DHRS</b>			<b>HMSV</b>		
	8, 10	10	■	■	2	548784	HMSV-54
	12, 16	16	■	■		548785	HMSV-55
	20, 25	25, 32	■	■		548786	HMSV-56
	<b>DPZ</b>	<b>DHRS</b>			<b>HAPG</b>		
	10, 16	16	■	–	2	163250	HAPG-1
	16	25	■	–		163251	HAPG-2
	20	25	■	–		163252	HAPG-3
	25, 32	32	■	–		163253	HAPG-4
	<b>DRRD</b>	<b>DHRS</b>			<b>DHAA</b>		
	8	10	■	■	2	2816591	DHAA-G-Q11-8-B2/B3-10
	10	10	■	■		2816068	DHAA-G-Q11-10-B2/B3-10
	12	10	■	■		2814790	DHAA-G-Q11-12-B2/B3-10
	12	16	■	■		2811183	DHAA-G-Q11-12-B2/B3-16
	16	16	■	■		1979085	DHAA-G-Q11-16-B2/B3-16
	16	25	■	■		1978889	DHAA-G-Q11-16-B2/B3-25
	20	25	■	■		1978443	DHAA-G-Q11-20-B2/B3-25
	20	32	■	■		1979912	DHAA-G-Q11-20-B2/B3-32
	25	25	■	■		1801802	DHAA-G-Q11-25-B2/B3-25
	25	32	■	■		1802969	DHAA-G-Q11-25-B2/B3-32
	32	32	■	■		1979992	DHAA-G-Q11-32-B2/B3-32
	32	40	■	■		1980014	DHAA-G-Q11-32-B2/B3-40
	35, 40	40	■	■		1980059	DHAA-G-Q11-35/40-B2/B3-40

1) Corrosion resistance class CRC 2 to Festo standard FN 940070


Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.



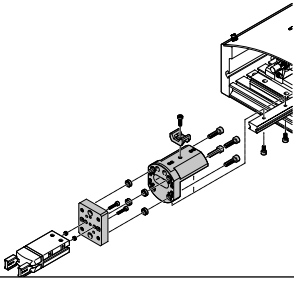


Accessories

Adapter kit  
HAPG, DHAA

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 **Note**  
The kit includes the individual mounting interface as well as the necessary mounting material.


Permissible drive/gripper combinations with adapter kit							Download CAD data → <a href="http://www.festo.com">www.festo.com</a>	
Combination	Drive size	Gripper size	Mounting option		Adapter kit CRC <sup>1)</sup>	Part no.	Type	
								
<b>HSP/DHRS</b>	<b>HSP</b>	<b>DHRS</b>			<b>HAPG</b>			
	12	10	■	–	2	192709	HAPG-60-S1	
	16	10	■	–		540881	HAPG-70-B	
	16	16	■	–		192706	HAPG-37-S1	
	25	16	■	–		540882	HAPG-71-B	
	25	16	■	–		192705	HAPG-36-S1	
	25	25	■	–		540882	HAPG-71-B	
<b>HSW/DHRS</b>	12, 16	10	■	–	2	192706	HAPG-37-S1	
		16	■	–		540882	HAPG-71-B	
	12, 16	16	■	–		192705	HAPG-36-S1	
						540882	HAPG-71-B	
<b>DSM/DHRS</b>	<b>DSM-...-FW</b>	<b>DHRS</b>			<b>HAPG</b>			
	6, 8, 10	10	■	■	2	187568	HAPG-34	
	<b>DSM-...</b>	<b>DHRS</b>			<b>HAPG</b>			
	12	16	■	■	2	163266	HAPG-17	
	16	16	■	■		163267	HAPG-18	
	16	25	■	■		163268	HAPG-19	
	25	25	■	■		163269	HAPG-20	
	25	32	■	■		163270	HAPG-21	
32	32	■	■	163271		HAPG-22		
<b>DSM-...-HD/DHRS</b>	<b>DSM-...-HD</b>	<b>DHRS</b>			<b>DHAA</b>			
	12	16	■	■	2	8072157	DHAA-G-R3-12-B18-10	
	12	10	■	■		8072172	DHAA-G-R3-12-B20-10	
	16	16	■	■		8071917	DHAA-G-R3-16-B18-10	
	16	25	■	■		8079173	DHAA-G-R3-16-B18-16	
	25	25	■	■		8071956	DHAA-G-R3-25-B18-16	
	25	32	■	■		8079201	DHAA-G-R3-25-B20-32	
	32	32	■	■		8079208	DHAA-G-R3-32-B18-25	
32	40	■	■	8079212		DHAA-G-R3-32-B20-40		

1) Corrosion resistance class CRC 2 to Festo standard FN 940070  
Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

Accessories



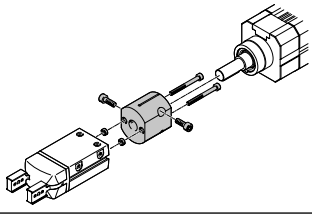
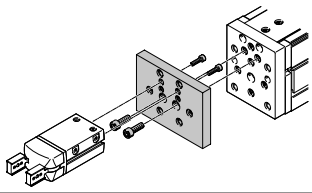
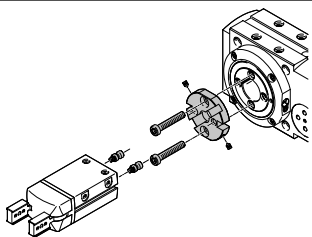
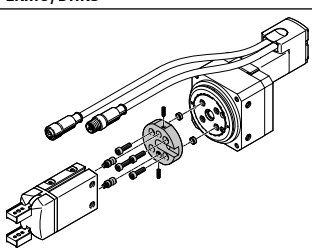
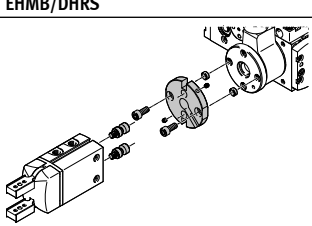
Adapter kit  
HAPG, HMSV, DHAA

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 **Note**  
The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit


Download CAD data → [www.festo.com](http://www.festo.com)

Combination	Drive size	Gripper size	Mounting option		Adapter kit CRC <sup>1)</sup>	Part no.	Type
							
	<b>DSL</b>	<b>DHRS</b>			<b>HAPG</b>		
	16	16	■	■	2	163266	HAPG-17
	20	16	■	■		163267	HAPG-18
	20	25	■	■		163268	HAPG-19
	25	25	■	■		163269	HAPG-20
	25	32	■	■		163270	HAPG-21
	32	32	■	■		163271	HAPG-22
	<b>EGSL</b>	<b>DHRS</b>			<b>HMSV</b>		
	35	10	■	■	2	548784	HMSV-54
	45, 55	16	■	■		1088262	HMSV-70
	75	25, 32	■	■		548785	HMSV-55
						548786	HMSV-56
	<b>ERMB</b>	<b>DHRS</b>			<b>HAPG</b>		
	20	25	■	■	2	184479	HAPG-SD2-3
	25	25	■	■		184482	HAPG-SD2-6
	20	32	■	■		184480	HAPG-SD2-4
	25	32	■	■		184483	HAPG-SD2-7
	32	32	■	■		184485	HAPG-SD2-9
	32	40	■	■		184486	HAPG-SD2-10
	<b>ERMO</b>	<b>DHRS</b>			<b>DHAA</b>		
	12	16	■	■	2	8072157	DHAA-G-R3-12-B18-10
	12	10	■	■		8072172	DHAA-G-R3-12-B20-10
	16	16	■	■		8071917	DHAA-G-R3-16-B18-10
	16	25	■	■		8079173	DHAA-G-R3-16-B18-16
	25	25	■	■		8071956	DHAA-G-R3-25-B18-16
	25	32	■	■		8079201	DHAA-G-R3-25-B20-32
	32	32	■	■		8079208	DHAA-G-R3-32-B18-25
	32	40	■	■		8079212	DHAA-G-R3-32-B20-40
	<b>EHMB</b>	<b>DHRS</b>			<b>HAPG</b>		
	20	32	■	■	2	184485	HAPG-SD2-9
	20	40	■	■		184486	HAPG-SD2-10
	25, 32	40	■	■		526027	HAPG-SD2-21

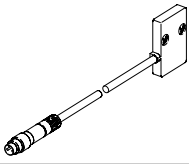
1) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

## Accessories

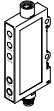
Ordering data						
	For size [mm]	Description	Weight [g]	Part no.	Type	PU <sup>1)</sup>
Centring sleeve ZBH						Data sheets → Internet: zbh
	10, 16	For centring the gripper during mounting	1	8146543	ZBH-5-B	10
	25		1	8146544	ZBH-7-B	
	32		1	8137184	ZBH-9-B	
	40		1	8137185	ZBH-12-B	




1) Packaging unit

Ordering data					
Type	For size	Weight [g]	Part no.	Type	
Position sensor SMH-S1					
	10	20	175712	SMH-S1-HGR10	Data sheets → Internet: smh-s1

## Signal converter SVE4 for position sensor SMH-S1

- Converts analogue signals into switching points
- Switching function freely programmable with teach-in
- Threshold value, hysteresis or window comparator

Ordering data							
Type	For size	Input connection	Output connection	Switching output	Weight [g]	Part no.	Type
Signal converter SVE4							
	10	Socket M8x1, 4-pin	Plug M8x1, 4-pin	2x PNP	19	544216	SVE4-HS-R-HM8-2P-M8
				2x NPN		544219	SVE4-HS-R-HM8-2N-M8

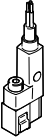
Ordering data – Connecting cables					
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
Connection between position sensor and signal converter					
	Straight socket, M8x1, 4-pin	Straight plug M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
Connection between signal converter and controller					
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
			5	541343	NEBU-M8G4-K-5-LE4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4

Accessories

Proximity switch for size 16 ... 40



Ordering data – Proximity switch for T-slot, magneto-resistive

Data sheets → Internet: smt

	Type of mounting	Electrical connection, outlet direction of connection	Switching output	Cable length [m]	Part no.	Type
<b>N/O contact</b>						
	Insertable in the slot lengthwise	Cable, 3-wire, lateral	PNP	2.5	547859	SMT-8G-PS-24V-E-2,5Q-OE
		Plug M8x1, 3-pin, lateral		0.3	547860	SMT-8G-PS-24V-E-0,3Q-M8D
		Cable, 3-wire, lateral	NPN	2.5	8065028	SMT-8G-NS-24V-E-2,5Q-OE
		Plug M8x1, 3-pin, lateral		0.3	8065027	SMT-8G-NS-24V-E-0,3Q-M8D

Ordering data – Connecting cables

Data sheets → Internet: nebu



	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

Position transmitter

The position transmitter continuously senses the position of the piston.  
It has an analogue output with an output signal relative to the piston position.



Ordering data – Position transmitter for T-slot

Data sheets → Internet: position transmitter

	For size	Position measuring range	Analogue output [V]   [mA]		Type of mounting	Electrical connection	Cable length [m]	Part no.	Type
	16 ... 40	0 ... 40	0 ... 10	–	Insertable in the slot from above	Plug M8x1, 4-pin, in-line	0.3	553744	SMAT-8M-U-E-0,3-M8D
	32, 40	0 ... 50	–	4 ... 20	Insertable in the slot from above	Plug M8x1, 4-pin, in-line	0.3	1531265	SDAT-MHS-M50-1L-SA-E-0.3-M8

Ordering data – Connecting cables

Data sheets → Internet: nebu

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
			5	541343	NEBU-M8G4-K-5-LE4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4