

## Toothed belt axis units ELGE

**FESTO**



This product is also available as a modular mechanical system  
Toothed belt axis ELGR-TB



## Key features

### At a glance

#### Plug and work with the Simplified Motion Series



The simplicity of pneumatics is now combined for the first time with the advantages of electric automation thanks to the Simplified Motion Series. These integrated drives are the perfect solution for all users who are looking for an electric alternative for very simple movement and positioning tasks between two mechanical end positions, but don't want the commissioning process for traditional electric drive systems that can often be quite complex.



There is no need for any software since operation is simply based on the "plug and work" principle. Digital I/O (DIO) and IO-Link are always automatically included – a product with two types of control as standard.

#### Integrated

The integrated electronics in the drive are at the heart of the Simplified Motion Series.

#### Easy

For commissioning, simply set all relevant parameters directly on the drive:

- Speed and force
- Reference end position and cushioning
- Manual operation

#### Standardised

Electrical connection via M12 plug design

- Power (4-pin): power supply for the motor
- Logic (8-pin): control signal, sensor signal and power for the integrated electronics

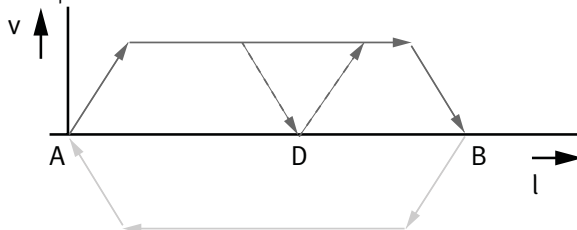
#### Connected

Use of extended functions possible via IO-Link:

- Remote configuration of motion parameters
- Copy and backup function for transferring parameters
- Read function for extended process parameters
- Freely definable intermediate position

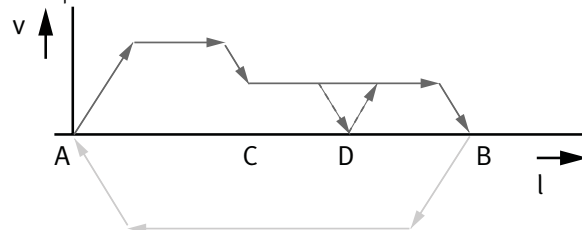
### The functions of the Simplified Motion Series

Basic profile for movement between two end positions: with speed control



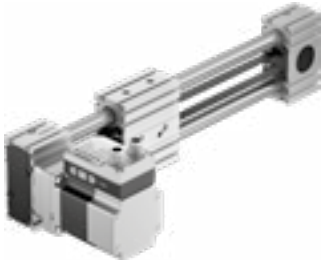
- These drives are designed for simple movements between two end positions.
- Proximity switches are required in order to implement any intermediate positions.
- With the intermediate position that can be freely configured via IO-Link, movements can be stopped at a freely defined point between the end positions, without the need for proximity switches or external stops

Extended motion profile for simplified press-fitting and clamping functions: with speed and force control



## Key features

## At a glance



- Without external servo drive: all the necessary electronic components are combined in the integrated drive
- Two control options integrated as standard: digital I/O and IO-Link
- Complete solution for simple movements between mechanical end positions
- Simplified commissioning: all parameters can be manually set directly on the drive
- No special expertise required for commissioning
- End-position feedback similar to that of a conventional proximity switch is integrated as standard
- Choice of motor mounting position on four sides
- Cost-optimised design for tasks that require simpler yet highly cost-efficient solutions with a service life of 5000 km

## The products in the Simplified Motion Series

Electric cylinder unit  
EPCE



Mini slide unit  
EGSS-BS-KF



Toothed belt axis unit  
ELGS-TB-KF



Electric cylinder unit  
EPCS



Mini slide unit with parallel motor mounting  
EGSS-BS-KF



Toothed belt axis unit  
ELGE



Electric cylinder unit with parallel motor mounting  
EPCS



Spindle axis unit  
ELGS-BS-KF



Rotary drive unit  
ERMS

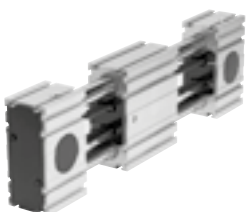


Spindle axis unit with parallel motor mounting  
ELGS-BS-KF



## Modular and flexible with motor, motor mounting kit and servo drive

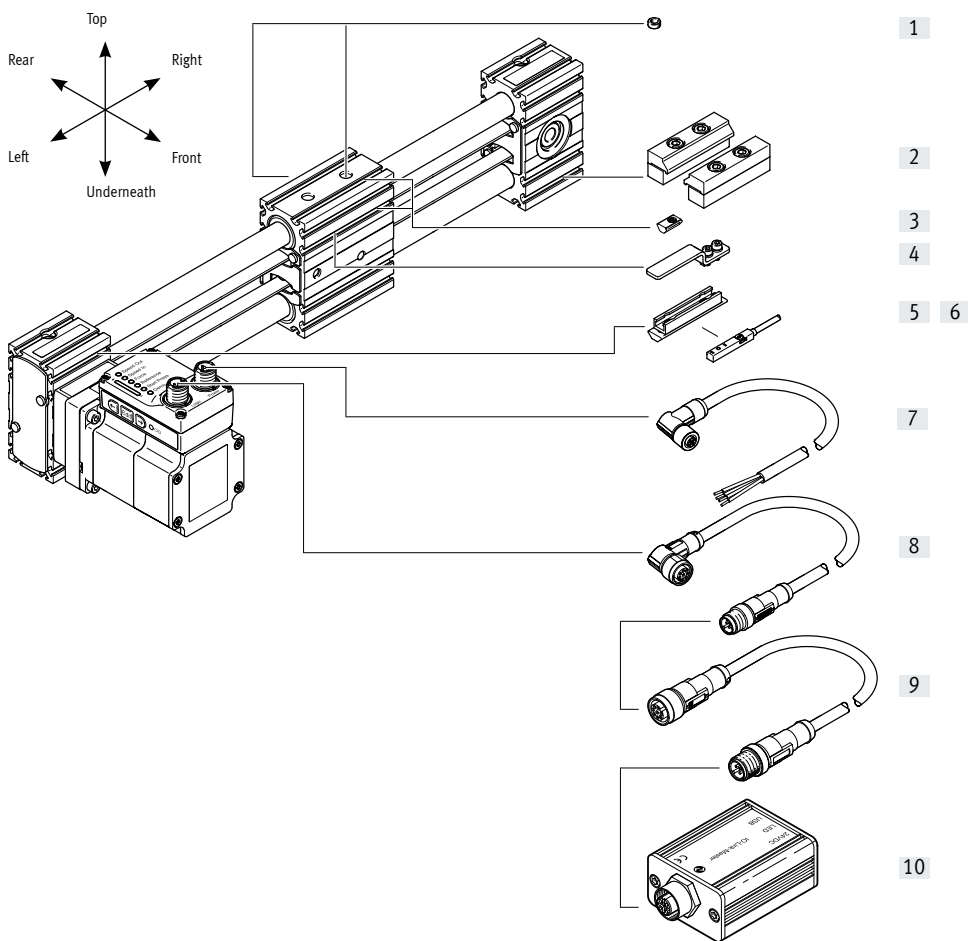
This product is also available within the Optimised Motion Series as toothed belt axis ELGR-TB:



Toothed belt axes for tasks that require simpler yet highly cost-efficient solutions in cost-optimised design with a long service life. Ideal for pick & place tasks and for transporting small loads of less than 15 kg.

- 1 driven slide, freely movable slides can be added as an option
- Extended guide, additional mounting options
- Free choice of flexible motor mounting on 4 sides
- Guide variants: recirculating ball bearing guide for moderate loads or plain-bearing guide for low loads
- Modular: individual combinations with motor, motor mounting kit and servo drive

Peripherals overview



Accessories			
Type/order code	Description		→ Page/Internet
[1] Centring sleeve ZBH	<ul style="list-style-type: none"> <li>For centring loads and attachments on the slide</li> <li>2 centring sleeves included in the scope of delivery of the axis</li> </ul>		21
[2] Profile mounting MUE	For mounting the axis on the bearing cap		20
[3] Slot nut NST	For mounting attachments		21
[4] Switch lug <sup>1)</sup> EAPM-L4-SLS	For sensing the slide position		20
[5] Sensor bracket <sup>1)</sup> EAPM-L4-SHS	Adapter for mounting the inductive proximity switches on the axis		20
[6] Proximity switch, T-slot <sup>1)</sup> SIES-8M	<ul style="list-style-type: none"> <li>Inductive proximity switch, for T-slot</li> <li>1 switch lug and 1 sensor bracket are included in the scope of delivery with the order code SA, SB</li> </ul>		21
[7] Supply cable NEBL-T12	For connecting load and logic supply		22
[8] Connecting cable NEBC-M12	For connection to a controller		22
[9] Adapter NEFC-M12G8	<ul style="list-style-type: none"> <li>Connection between the motor and the IO-Link master</li> <li>Only recommended for use with IO-Link port class A master</li> </ul>		22
[10] IO-Link master USB CDSU-1	For straightforward use of the mini slide unit via IO-Link		22

1) Proximity switches are optional and only required in order to sense any intermediate positions.

Peripherals overview

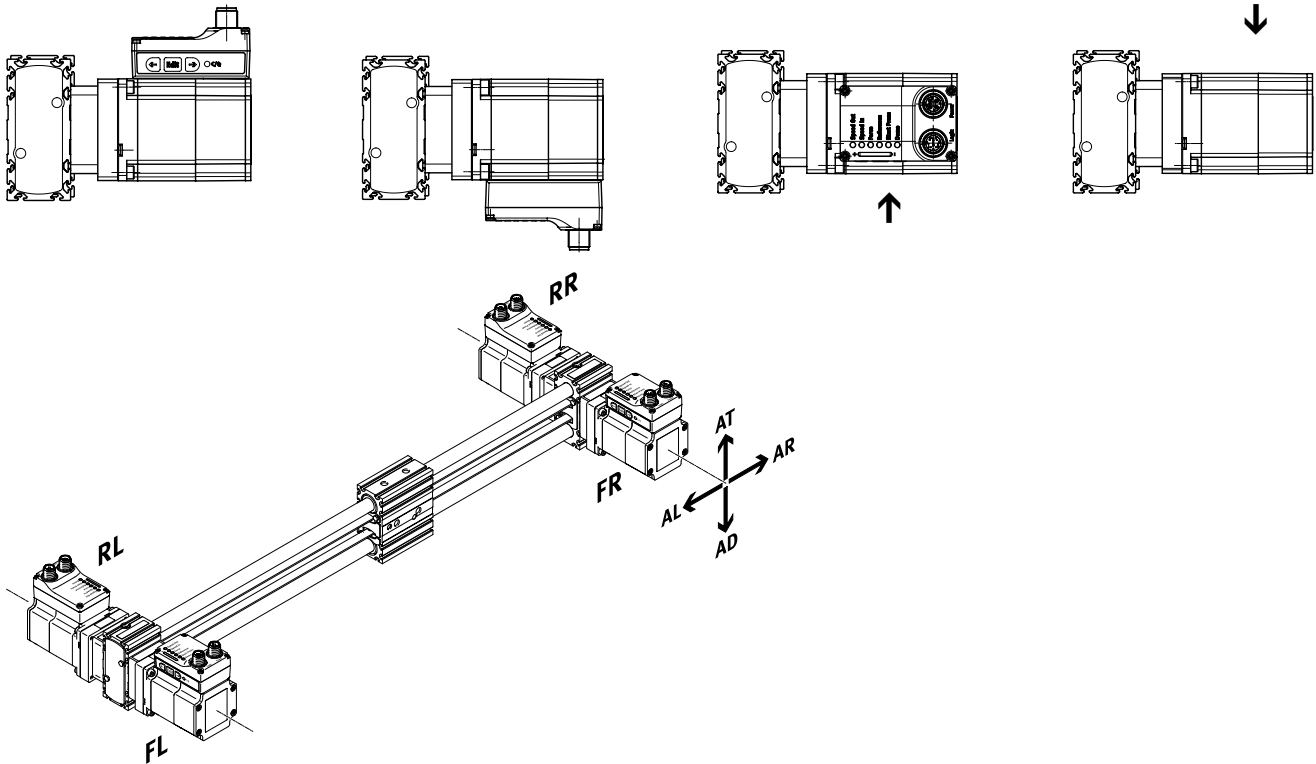
Motor attachment variants

[AT] Top

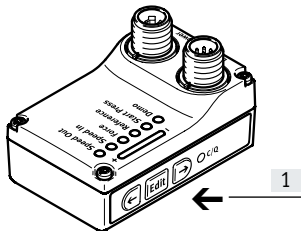
[AD] Underneath

[AL] Left

[AR] Right



Control elements



[1] Pushbutton actuators for parameterisation and control

Possible combinations with Festo drives

Electric cylinder EPCO on toothed belt axis unit ELGE



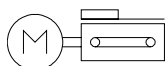
Size		Accessories			
[1] EPCO	[2] ELGE	Slot nut	Centring sleeve	Screw	Washer
16	35	NST-3-M3 (x4)	ZBH-7 (x2)	M3x10 (x4)	-



## Type codes

<b>001</b>	<b>Series</b>	
ELGE	Gantry axis	
<b>002</b>	<b>Drive system</b>	
TB	Toothed belt	
<b>003</b>	<b>Guide</b>	
	Recirculating ball bearing guide	
<b>004</b>	<b>Size</b>	
35	35	
<b>005</b>	<b>Stroke</b>	
50	50	
100	100	
150	150	
200	200	
250	250	
300	300	
350	350	
400	400	
450	450	
500	500	
550	550	
600	600	
650	650	
700	700	
750	750	
800	800	
<b>006</b>	<b>Stroke reserve</b>	
OH	0 mm	
<b>007</b>	<b>Motor type</b>	
ST	Stepper motor ST	
<b>008</b>	<b>Controller</b>	
M	Integrated	
<b>009</b>	<b>Control panel</b>	
H1	Integrated	

<b>010</b>	<b>Bus protocol/activation</b>	
PLK	PNP and IO-Link®	
NLK	NPN and IO-Link®	
<b>011</b>	<b>End-position sensing</b>	
AA	With integrated end-position sensing	
<b>012</b>	<b>Cable outlet direction</b>	
AT	Top	
AD	Underneath	
AL	Left	
AR	Right	
<b>013</b>	<b>Motor position</b>	
FR	Front right	
FL	Front left	
RR	Rear right	
RL	Rear left	
<b>014</b>	<b>Profile mounting</b>	
...MA	1 ... 2	
<b>015</b>	<b>Proximity sensor, inductive, slot 8, N/O contact, cable 7.5 m</b>	
...SA	0 ... 6	
<b>016</b>	<b>Proximity sensor, inductive, slot 8, N/C contact, cable 7.5 m</b>	
...SB	1 ... 6	
<b>017</b>	<b>Slot nut for mounting slot</b>	
...NM	1 ... 99	
<b>018</b>	<b>Electrical accessories</b>	
	None	
L1	Adapter for operation as IO-Link® device	
<b>019</b>	<b>Operating instructions</b>	
	With operating instructions	
DN	No operating instructions	

## Datasheet



-  - Size  
35
-  - Stroke length  
50 ... 800 mm

**General technical data**

Size	35	
Design	Electromechanical axis with toothed belt and integrated drive	
Motor type	Stepper motor	
Guide	Recirculating ball bearing guide	
Mounting position	Horizontal	
Working stroke	[mm]	50 ... 800
Stroke reserve	[mm]	0
Additional functions	Built-in end-position sensing	
	User interface	
Display	LED	
Homing	Positive fixed stop block	
	Negative fixed stop block	
Type of mounting	With female thread	
	With accessories	
	With centring pin, centring sleeve	
Max. cable length		
Inputs/outputs	[m]	15
IO-Link operation	[m]	20

**Mechanical data**

Size	35	
Max. payload	[kg]	2.8
Max. feed force $F_x$	[N]	50
Speed <sup>1)</sup>	[m/s]	1.2
Speed "Speed Press" <sup>2)</sup>	[m/s]	0.024
Max. acceleration <sup>2)</sup>	[m/s <sup>2</sup> ]	8.5
Repetition accuracy	[mm]	±0.1
Position sensing	Via proximity switch	
	Via IO-Link	

1) It is not possible to reach the maximum speed of 1.2 m/s with strokes < 250 mm.  
Adjustable in increments of 10%

2) Unchangeable parameter

## Datasheet

Toothed belt		
Size		35
Pitch	[mm]	2
Elongation <sup>1)</sup>	[%]	0.094
Effective diameter	[mm]	18.46
Feed constant	[mm/rev]	58

1) At max. feed force

Electrical data		
Size		35
Motor		
Nominal voltage DC	[V]	24 (±15%)
Nominal current	[A]	5.3
Max. current consumption (load)	[A]	5.3
Max. current consumption (logic)	[mA]	300
Encoder		
Rotor position sensor		Absolute encoder, single turn
Rotor position sensor measuring principle		Magnetic
Rotor position encoder resolution	[bit]	16

Interfaces		
Size		35
Parameterisation interface		
IO-Link		Yes
User interface		Yes
Digital inputs		
Number		2
Switching logic		PNP
		NPN
Characteristics		Not galvanically isolated
		Configurable
Specification		Based on IEC 61131-2, type 1
Operating range	[V]	24
Digital outputs		
Number		2
Switching logic		PNP
		NPN
Rotor position sensor		Absolute encoder, single turn
Characteristics		Not galvanically isolated
		Configurable
Max. current	[mA]	100



## Datasheet

Technical data – IO-Link		
Size		35
SIO mode support		Yes
Communication mode		COM3 (230.4 kBd)
Connection technology		Plug
Port class		A
No. of ports		1
Process data width OUT	[byte]	2
Process data content OUT	[bit]	1 (Move in)
	[bit]	1 (Move out)
	[bit]	1 (Move Intermediate)
	[bit]	1 (Quit Error)
Process data width IN	[byte]	2
Process data content IN	[bit]	1 (State Device)
	[bit]	1 (State Move)
	[bit]	1 (State in)
	[bit]	1 (State out)
	[bit]	1 (State Intermediate)
Service data content IN	[bit]	32 (Force)
	[bit]	32 (Position)
	[bit]	32 (Speed)
Minimum cycle time	[ms]	1
Data memory required	[kilobyte]	0.5
Protocol version		Device V 1.1

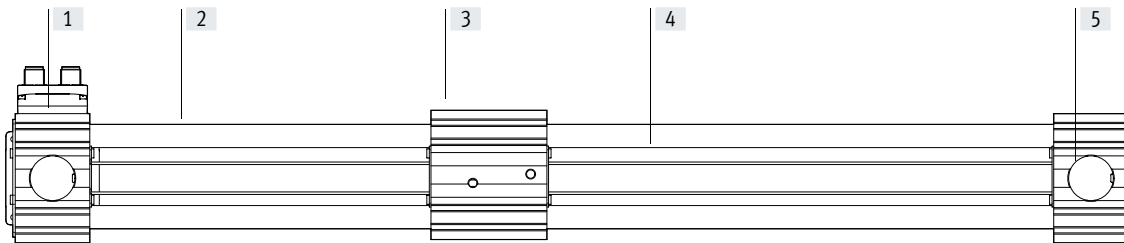
Operating and environmental conditions		
Size		35
Insulation class		B
Ambient temperature	[°C]	0 ... +50
Storage temperature	[°C]	-20 ... +60
Note on ambient temperature		Above an ambient temperature of 30°C, the power must be reduced by 2% per K
Temperature monitoring		Switch-off for excessive temperature
		Integrated precise CMOS temperature sensor with analogue output
Relative humidity	[%]	0 ... 90
Protection class		III
Degree of protection		IP20
Duty cycle	[%]	100
CE marking (see declaration of conformity)		To EU EMC Directive for EMCS-ST → festo.com/sp
		To EU RoHS Directive
UKCA marking (see declaration of conformity)		To UK instructions for EMC
		To UK RoHS instructions
KC mark		KC EMC
Certification		RCM
Vibration resistance		Transport application test with severity level 1 to FN 942017-4 and EN 61800-2 and EN 61800-5-1
Shock resistance		Shock test with severity level 1 to FN 942017-5 and EN 61800-2
Maintenance interval		Lifetime lubrication

## Datasheet

Weight		
Size		35
Basic weight at 0 mm stroke	[g]	2490
Additional weight per 10 mm stroke	[g]	25
Additional weight of moving mass per 10 mm stroke	[g]	0.31

## Materials

Sectional view



Axis		
[1]	Bearing cap, profile	Anodised wrought aluminium alloy
[2]	Guide rods	Hardened and hard-chromium plated tempered steel
[3]	Slide, profile	Anodised wrought aluminium alloy
[4]	Toothed belt	Polychloroprene with glass cord and nylon coating
[5]	Belt pulley	High-alloy stainless steel
	PWIS conformity	VDMA24364 zone III
	Note on materials	RoHS-compliant

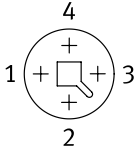
## Datasheet

### Pin allocation

#### Power supply

Plug

M12x1, 4-pin, T-coded to EN 61076-2-111

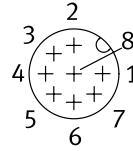


Pin	Function
1	Power voltage supply (24 V DC)
2	Reference potential, power voltage supply (GND)
3	Reserved, do not connect
4	Functional earth (FE)

#### Logic interface

Plug

M12x1, 8-pin, A-coded to EN 61076-2-101



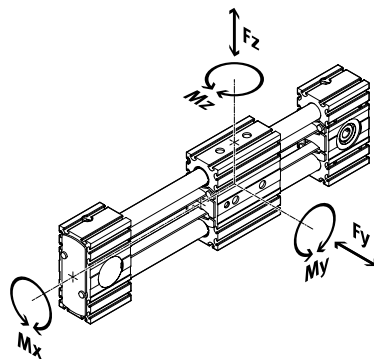
When used with digital I/O	
Pin	Function
1	Logic voltage supply (24 V DC)
2	Digital output 1 (State "In")
3	Digital output 2 (State "Out")
4	Reference potential, logic voltage supply (GND)
5	Digital input 1 (Move "In")
6	Digital input 2 (Move "Out")
7	Reserved, do not connect
8	Reference potential, logic voltage supply (GND)

When used with IO-Link	
Pin	Function
1	L+ IO-Link power supply (24 V DC)
2	Reserved, do not connect
3	C/Q communication with the IO-Link master
4	L – Reference potential, IO-Link power supply (0 V)
5	Reserved, do not connect
6	Reserved, do not connect
7	Reserved, do not connect
8	L – Reference potential, IO-Link power supply (0 V)

## Datasheet


### Load values

The indicated forces and torques refer to the centre of the guide. The point of application of force is the point where the centre of the guide and the longitudinal centre of the slide intersect. These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



Max. permissible forces and torques for the guide calculation, for a service life of 5000 km

Size		35
F <sub>y</sub> max.	[N]	50
F <sub>z</sub> max.	[N]	50
M <sub>x</sub> max.	[Nm]	2.5
M <sub>y</sub> max.	[Nm]	8
M <sub>z</sub> max.	[Nm]	8

 **Note**

For a guide system to have a service life of 5000 km, the load comparison factor must have a value of  $f_v \leq 1$ , based on the maximum permissible forces and torques for a service life of 5000 km.

This formula can be used to calculate a guide value.

The engineering software "Electric Motion Sizing" is available for more precise calculations → [www.festo.com](http://www.festo.com)

If the axis is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

Calculating the load comparison factor:

$$f_v = \frac{|F_{y1}|}{F_{y2}} + \frac{|F_{z1}|}{F_{z2}} + \frac{|M_{x1}|}{M_{x2}} + \frac{|M_{y1}|}{M_{y2}} + \frac{|M_{z1}|}{M_{z2}} \leq 1$$

F<sub>1</sub>/M<sub>1</sub> = dynamic value

F<sub>2</sub>/M<sub>2</sub> = maximum value

## Datasheet

### Calculating the service life

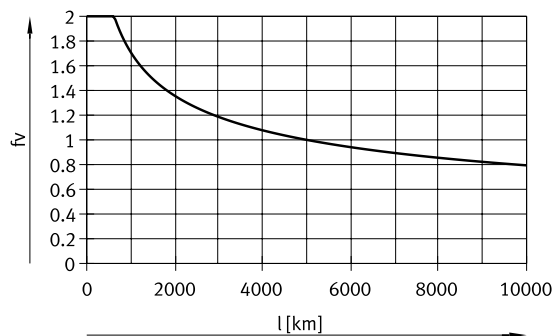
The service life of the guide depends on the load. To be able to make a statement as to the service life of the guide, the graph below plots the load comparison factor  $f_v$  against the service life.

These values are only theoretical. You must consult your local Festo contact for a load comparison factor  $f_v$  greater than 1.

### Load comparison factor $f_v$ as a function of service life $l$

Example:

A user wants to move an  $x$  kg load. Using the formula (→ page 4) gives a value of 1.5 for the load comparison factor  $f_v$ . According to the graph, the guide would have a service life of approx. 1 500 km. Reducing the acceleration reduces the  $M_y$  and  $M_z$  values. A load comparison factor  $f_v$  of 1 now gives a service life of 5000 km.



### Service life of the motor

The service life of the motor at nominal power is 20000 h.

## Datasheet

## Sizing example

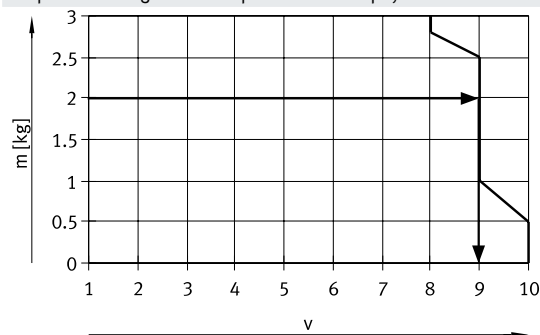
Application data:

- Payload: 2 kg
- Mounting position: horizontal
- Motor mounting position: axial
- Stroke: 600 mm
- Max. permitted positioning time: 1 s (one direction)

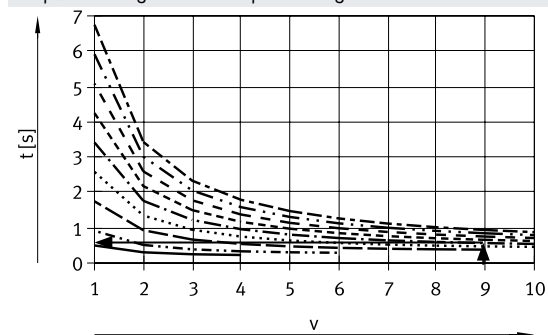
Step 1: Selecting the size from the table → page 7

## Mechanical data

Size		35
Max. payload	[kg]	2.8

Step 2: Selecting the max. speed level  $v$  for payload  $m$ 

Horizontal

Step 3: Reading off the min. positioning time  $t$  for stroke  $l$ 

- $l = 50$  mm
- · - · -  $l = 100$  mm
- - -  $l = 200$  mm
- · · · ·  $l = 300$  mm
- · - · -  $l = 400$  mm
- - -  $l = 500$  mm
- - -  $l = 600$  mm
- · - · -  $l = 700$  mm
- · - · -  $l = 800$  mm

→ Max. speed level for payload: level 9

→ Min. positioning time for 600 mm at level 9: 0.75 s

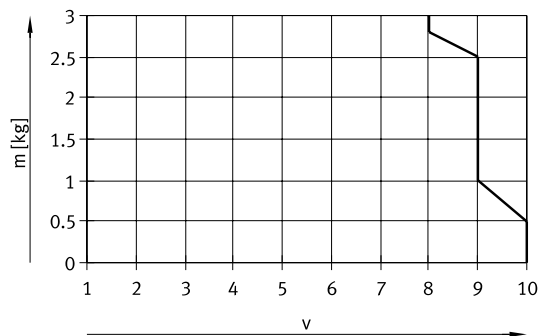
## Result

The application can be implemented using ELGE-TB-35-600. A minimum positioning time (one direction) of 0.75 s is achieved. Longer positioning times can be selected at any time using a lower speed level.

Datasheet

Mass m as a function of speed level v

Size 35



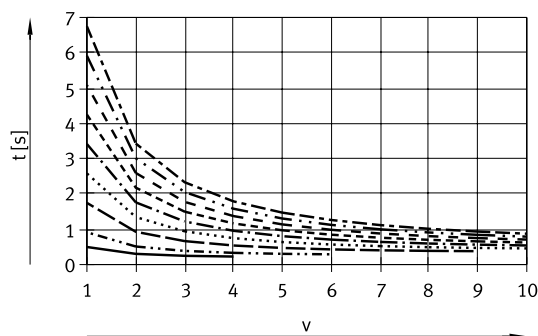
Horizontal

Note:

The lines represent the maximum values. The lower speed levels can be set at any time.

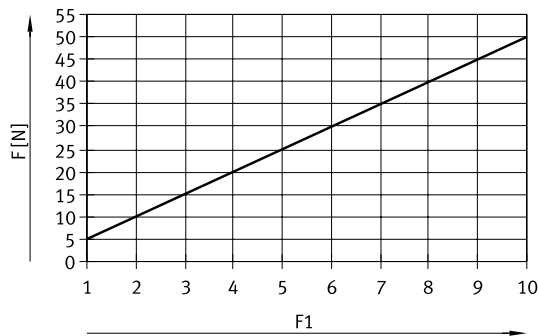
Positioning time t as a function of speed level v and stroke l

Size 35



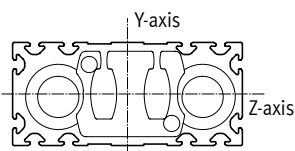
- l = 50 mm
- · - · - l = 100 mm
- - - l = 200 mm
- · · · · l = 300 mm
- · - · - l = 400 mm
- - - l = 500 mm
- · - · - l = 600 mm
- · - · - l = 700 mm
- · - · - l = 800 mm

Feed force F as a function of force level F1



ELGE-TB-35

2nd moments of area



Size		35
$I_y$	[mm <sup>4</sup> ]	$4.19 \times 10^3$
$I_z$	[mm <sup>4</sup> ]	$3.77 \times 10^3$

Recommended deflection limits

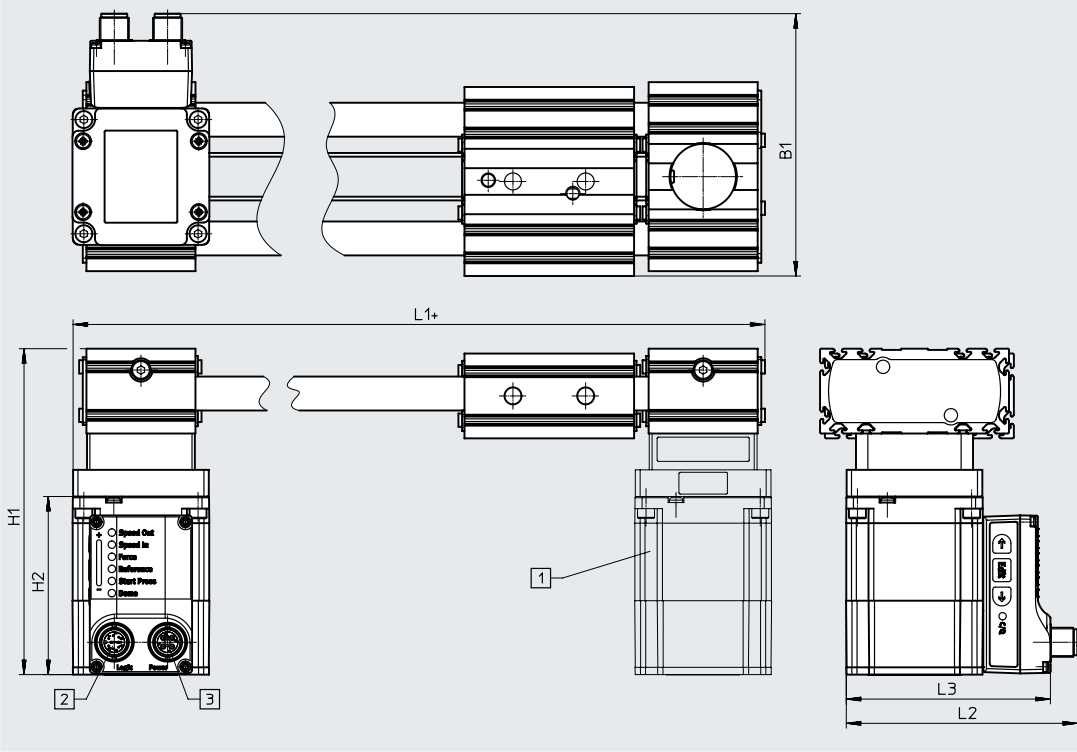
Adherence to a maximum deflection of 0.5 mm is recommended so as not to impair the functionality of the axes. Greater deformation can result in increased friction, greater wear and reduced service life.

Datasheet

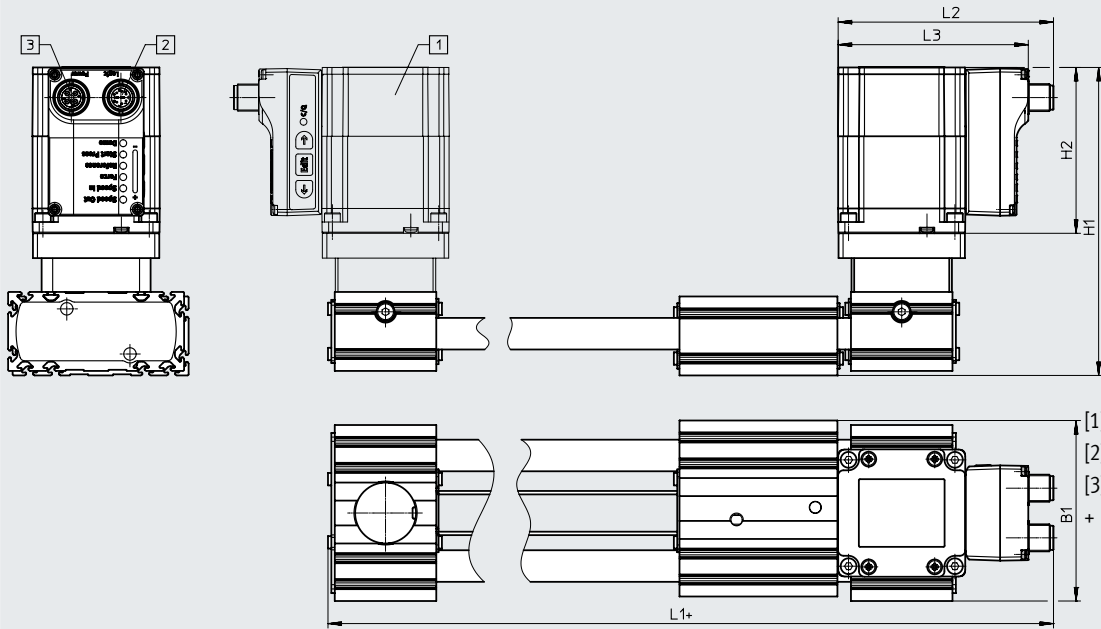
Dimensions – With motor

Download CAD data → [www.festo.com](http://www.festo.com)

ELGE-...-AT/AD



ELGE-...-AR/AL



- [1] Motor
  - [2] Connection to logic interface
  - [3] Connection to power supply
- = plus stroke length

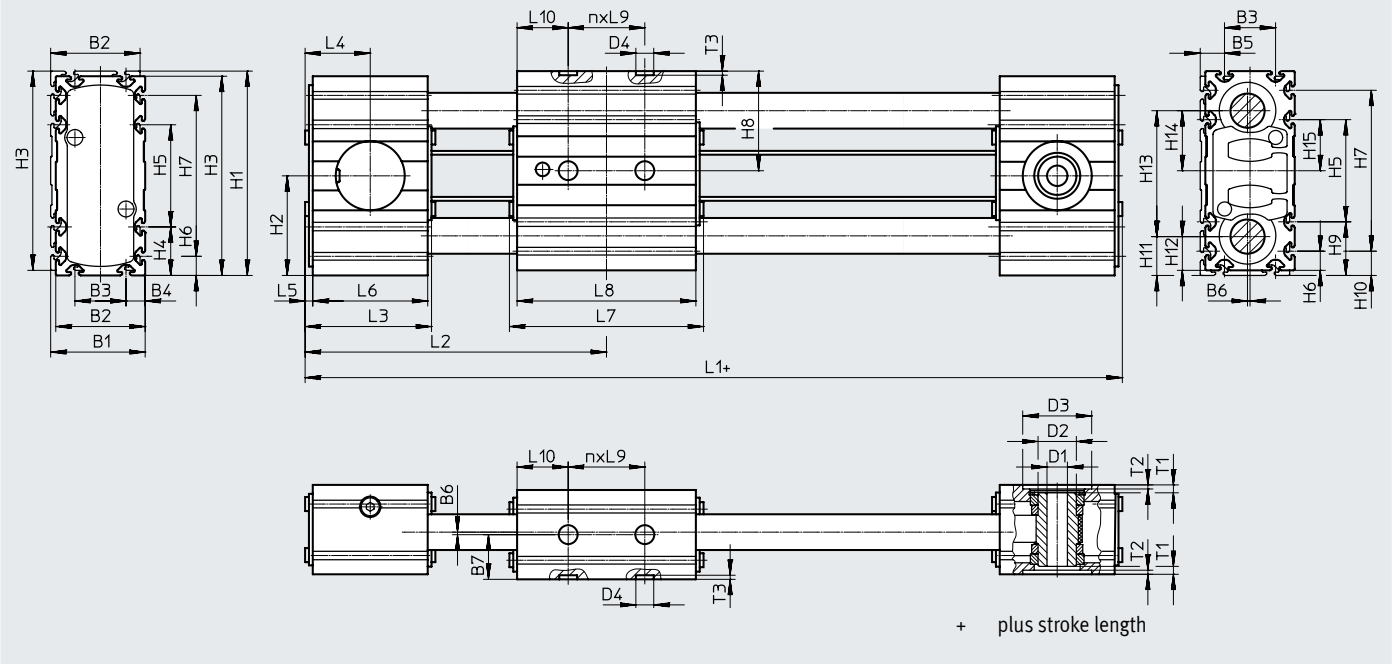
Size	B1	H1	H2	L1	L2	L3
ELGE-...-AT-FL	108.3	134.5	73.5	180.7	95.6	84.3
ELGE-...-AD-FR	108.3	134.5	73.5	180.7	95.6	84.3
ELGE-...-AR-RR	80	136.5	73.5	219.8	95.6	84.3
ELGE-...-AL-RL	80	136.5	73.5	219.8	95.6	84.3



Datasheet

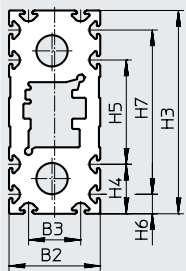
Dimensions

Download CAD data → [www.festo.com](http://www.festo.com)



Profile

ELGR-35



Size	B1	B2	B3	B4	B5	B6	B7	D1 ∅ H7	D2 ∅	D3 ∅ H7	D4 ∅ H7	H1	H2	H3	H4	H5	H6
35	37	35	20	7.5	9.5	1	17.5	8	15	27	7	80	39	78	19	40	7.5

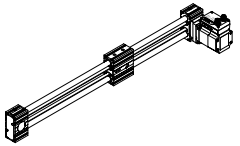
  

Size	H7	H8	H9	H10	H11	H12	H13	H14	H15	L3	L4	L5	L6	L9	T1	T2	T3 +0.1
35	63	39	21	9.5	15.5	13.5	49	23.5	20	51	25.5	3	45	30	3.1	1.6	1.6

Size	L1		L2		L7		L8		L10		n	
35	178		89		76		70		20		1	

## Ordering data

Ordering data	Size	Stroke	Part no.	Type
	35	100	8083931	ELGE-TB-35-100-0H-ST-M-H1-PLK-AA-AT-FR
		200	8083932	ELGE-TB-35-200-0H-ST-M-H1-PLK-AA-AT-FR
		300	8083933	ELGE-TB-35-300-0H-ST-M-H1-PLK-AA-AT-FR
		400	8083934	ELGE-TB-35-400-0H-ST-M-H1-PLK-AA-AT-FR
		500	8083935	ELGE-TB-35-500-0H-ST-M-H1-PLK-AA-AT-FR
		600	8083936	ELGE-TB-35-600-0H-ST-M-H1-PLK-AA-AT-FR

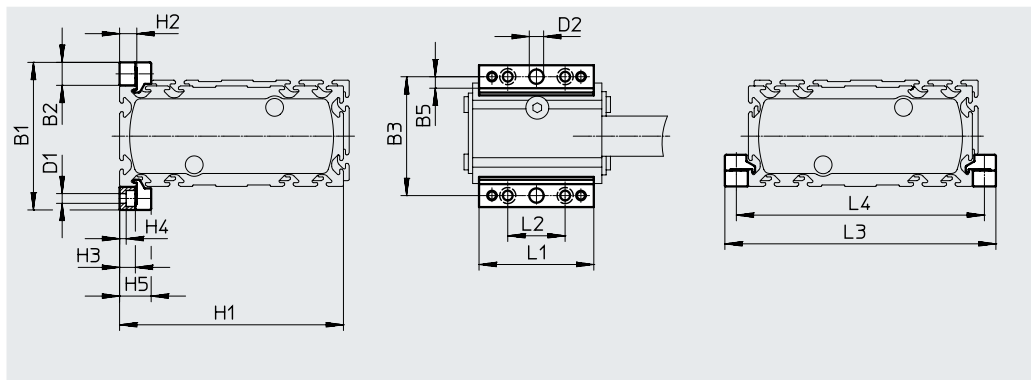
## Ordering data

Ordering table		Conditions	Code	Enter code
Size	35			
Module no.	8083929			
Series	ELGE		ELGE	ELGE
Drive system	Toothed belt		-TB	-TB
Guide	Recirculating ball bearing guide			
Size	35		-...	
Stroke [mm]	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800		-...	
Stroke reserve [mm]	0		-OH	-OH
Motor type	Stepper motor ST		-ST	-ST
Controller	Integrated		-M	-M
Operator panel	Integrated		-H1	-H1
Bus protocol/control	NPN and IO-Link		-NLK	
	PNP and IO-Link		-PLK	
End-position sensing	With integrated end-position sensing		-AA	AA
Cable outlet direction	Top		-AT	
	Underneath		-AD	
	Left		-AL	
	Right		-AR	
Motor position	Front left		-FL	
	Front right		-FR	
	Rear left		-RL	
	Rear right		-RR	
Profile mounting	None			
	1 ... 2		+...MA	
Proximity switch (SIES), inductive, slot type 8, N/O contact, cable 7.5 m, incl. switch lug and sensor bracket	None			
	1 ... 6		...SA	
Proximity switch (SIES), inductive, slot type 8, N/C contact, cable 7.5 m, incl. switch lug and sensor bracket	None			
	1 ... 6		...SB	
Slot nut, mounting slot	None			
	1 ... 99		...NM	
Electrical accessories	None			
	Adapter for operation as IO device		+L1	
Operating instructions	With operating instructions			
	Without operating instructions		DN	

Accessories

**Profile mounting MUE**  
(order code MA)

Material:  
Anodised aluminium  
RoHS-compliant

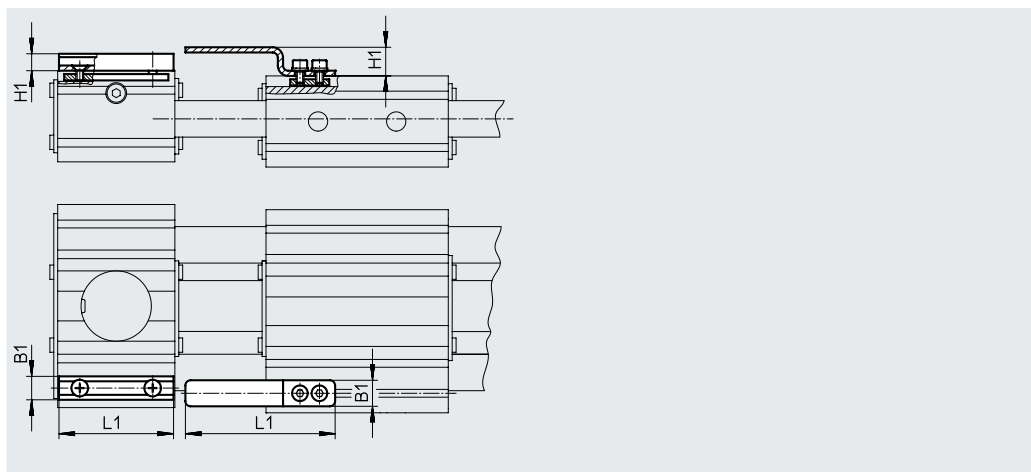


Dimensions and ordering data											
For size	B1	B2	B3	B5	D1 ∅	D2 ∅ H7	H1	H2	H3	H4	
35	51	8	43	4	3.4	5	78	6	5.5	2.3	

For size	H5	L1	L2	L3	L4	Weight [g]	Part no.	Type
35	11	40	20	94	86	20	558042	MUE-50



**Sensor bracket EAPM-...-SHS,**  
**switch lug EAPM-...-SLS**  
(order code SA/SB)

Material:  
Switch lug: Galvanised steel  
Sensor bracket: Anodised wrought  
aluminium alloy  
RoHS-compliant



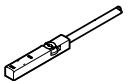
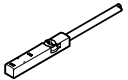
Dimensions and ordering data							
For size	B1	H1	L1	Weight [g]	Part no.	Type	
<b>Sensor bracket</b>							
35	9	6.5	44	20	567537	EAPM-L4-SHS	
<b>Switch lug</b>							
35	10	11	57.5	15	567538	EAPM-L4-SLS	



## Accessories


Ordering data						
	For size	Comment	Order code	Part no.	Type	PJ <sup>1)</sup>
<b>Slot nut NST</b>						
	35	For mounting slot	NM	558045	NST-3-M3	1
<b>Centring sleeve ZBH<sup>2)</sup></b>						
	35	For slide	–	8146544	ZBH-7-B	10

1) Packaging unit

2) 2 centring sleeves included in the scope of delivery of the axis


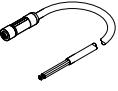
Ordering data – Proximity switches for T-slot, inductive							Datasheets → Internet: sies	
	Type of mounting	Electrical connection	Switching output	Cable length [m]	Order code	Part no.	Type	
<b>N/O</b>								
	Inserted in the slot from above, flush with the cylinder profile	Cable, 3-wire	PNP	7.5	SA	551386	SIES-8M-PS-24V-K-7.5-OE	
		Plug M8x1, 3-pin		0.3		–	551387	SIES-8M-PS-24V-K-0.3-M8D
		Cable, 3-wire	NPN	7.5	–	551396	SIES-8M-NS-24V-K-7.5-OE	
		Plug M8x1, 3-pin		0.3		–	551397	SIES-8M-NS-24V-K-0.3-M8D
<b>N/C</b>								
	Inserted in the slot from above, flush with the cylinder profile	Cable, 3-wire	PNP	7.5	SB	551391	SIES-8M-PO-24V-K-7.5-OE	
		Plug M8x1, 3-pin		0.3		–	551392	SIES-8M-PO-24V-K-0.3-M8D
		Cable, 3-wire	NPN	7.5	–	551401	SIES-8M-NO-24V-K-7.5-OE	
		Plug M8x1, 3-pin		0.3		–	551402	SIES-8M-NO-24V-K-0.3-M8D



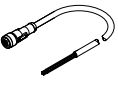
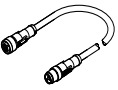
Ordering data – Connecting cables					Datasheets → Internet: nebu	
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type	
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3	
			5.0	541334	NEBU-M8G3-K-5-LE3	
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3	
			5.0	541341	NEBU-M8W3-K-5-LE3	


 **Note**

Proximity switches are optional and only required in order to sense any intermediate positions.

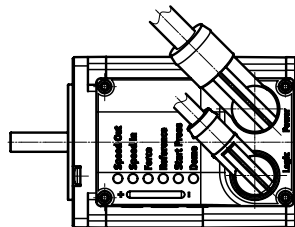
## Accessories


Ordering data – Supply cables					Datasheets → Internet: nebl
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Angled socket, M12x1, 4-pin	Cable, open end, 4-wire	2	8080778	NEBL-T12W4-E-2-N-LE4
			5	8080779	NEBL-T12W4-E-5-N-LE4
			10	8080780	NEBL-T12W4-E-10-N-LE4
			15	8080781	NEBL-T12W4-E-15-N-LE4
	Straight socket, M12x1, 4-pin	Cable, open end, 4-wire	2	8080790	NEBL-T12G4-E-2-N-LE4
			5	8080791	NEBL-T12G4-E-5-N-LE4
			10	8080792	NEBL-T12G4-E-10-N-LE4
			15	8080793	NEBL-T12G4-E-15-N-LE4


Ordering data – Connecting cables					Datasheets → Internet: nebc
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Angled socket, M12x1, 8-pin	Cable, open end, 8-wire	2	8094476	NEBC-M12W8-E-2-N-B-LE8
			5	8094478	NEBC-M12W8-E-5-N-B-LE8
			10	8094481	NEBC-M12W8-E-10-N-B-LE8
			15	8094479	NEBC-M12W8-E-15-N-B-LE8
		Straight plug, M12x1, 8-pin	2	8080786	NEBC-M12W8-E-2-N-M12G8
			5	8080787	NEBC-M12W8-E-5-N-M12G8
			10	8080788	NEBC-M12W8-E-10-N-M12G8
			15	8080789	NEBC-M12W8-E-15-N-M12G8
	Straight socket, M12x1, 8-pin	Cable, open end, 8-wire	2	8094480	NEBC-M12G8-E-2-N-B-LE8
			5	8094477	NEBC-M12G8-E-5-N-B-LE8
			10	8094482	NEBC-M12G8-E-10-N-B-LE8
			15	8094475	NEBC-M12G8-E-15-N-B-LE8
		Straight plug, M12x1, 8-pin	2	8080782	NEBC-M12G8-E-2-N-M12G8
			5	8080783	NEBC-M12G8-E-5-N-M12G8
			10	8080784	NEBC-M12G8-E-10-N-M12G8
			15	8080785	NEBC-M12G8-E-15-N-M12G8

 **Note**

The cables are positioned at a 45° angle to the axis.



Ordering data – IO-Link master USB					Datasheets → Internet: cdsu
	Description	Cable length [m]	Part no.	Type	
	<ul style="list-style-type: none"> <li>For using the unit with IO-Link</li> <li>An external power supply plug is also required (not included in the scope of delivery)</li> </ul>	0.3	8091509	CDSU-1	

Ordering data – Adapter					Datasheets → Internet: nefc
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Straight socket, M12x1, 8-pin	<ul style="list-style-type: none"> <li>Straight plug, M12x1, 5-pin</li> <li>Only recommended for use with IO-Link port class A master</li> </ul>	0.3	8080777	NEFC-M12G8-0.3-M12G5-LK